

Subspace

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# In Chapter 4 .....

The same vector or operation is represented differently when they are in different coordinate systems.

民濕寢則腰疾偏死，鱗然乎哉？木處則惴慄恂懼，  
猿猴然乎哉？三者孰知正處？民食芻豢，麋鹿食  
薦，螂蛆甘帶，鴟鴞嗜鼠，四者孰知正味？猿獼  
狙以為雌，麋與鹿交，鱗與魚游。毛嫱、西施，  
人之所美也；魚見之深入，鳥見之高飛，麋鹿見  
之決驟，四者孰知天下之正色哉？《莊子·齊物論》

Subspace

# Reference

- Textbook: chapter 4.1

# Subspace

- A vector set  $V$  is called a subspace if it has the following three properties:
- 1. The zero vector  $\mathbf{0}$  belongs to  $V$
- 2. If  $\mathbf{u}$  and  $\mathbf{w}$  belong to  $V$ , then  $\mathbf{u}+\mathbf{w}$  belongs to  $V$

Closed under (vector) addition

- 3. If  $\mathbf{u}$  belongs to  $V$ , and  $c$  is a scalar, then  $c\mathbf{u}$  belongs to  $V$

Closed under scalar multiplication

$2+3$  is linear combination

# Examples

$$W = \left\{ \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix} \in \mathcal{R}^3 : 6w_1 - 5w_2 + 4w_3 = 0 \right\} \quad \text{Subspace?}$$

Property 1.  $\mathbf{0} \in W \longrightarrow 6(0) - 5(0) + 4(0) = 0$

Property 2.  $\mathbf{u}, \mathbf{v} \in W \Rightarrow \mathbf{u} + \mathbf{v} \in W$

$$\begin{aligned} \mathbf{u} &= [u_1 \ u_2 \ u_3]^T, \mathbf{v} = [v_1 \ v_2 \ v_3]^T & \mathbf{u} + \mathbf{v} &= [u_1 + v_1 \ u_2 + v_2 \ u_3 + v_3]^T \\ 6(u_1 + v_1) - 5(u_2 + v_2) + 4(u_3 + v_3) & & & \\ &= (6u_1 - 5u_2 + 4u_3) + (6v_1 - 5v_2 + 4v_3) = 0 + 0 = 0 \end{aligned}$$

Property 3.  $\mathbf{u} \in W \Rightarrow c\mathbf{u} \in W$

$$6(cu_1) - 5(cu_2) + 4(cu_3) = c(6u_1 - 5u_2 + 4u_3) = c0 = 0$$

# Examples

$$V = \{c\mathbf{w} \mid c \in \mathcal{R}\} \quad \text{Subspace?}$$

$$\mathcal{S}_1 = \left\{ \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} \in \mathcal{R}^2 : w_1 \geq 0 \text{ and } w_2 \geq 0 \right\}$$

Subspace?  $\mathbf{u} \in \mathcal{S}_1, \mathbf{u} \neq \mathbf{0} \Rightarrow -\mathbf{u} \notin \mathcal{S}_1$

$$\mathcal{S}_2 = \left\{ \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} \in \mathcal{R}^2 : w_1^2 = w_2^2 \right\}$$

Subspace?  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix} \in \mathcal{S}_2$  but  $\begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} -1 \\ 1 \end{bmatrix} \notin \mathcal{S}_2$

$\mathcal{R}^n$  Subspace?

$\{\mathbf{0}\}$  Subspace? zero subspace

# Subspace v.s. Span

- The span of a vector set is a subspace

$$\text{Let } S = \{w_1, w_2, \dots, w_k\} \quad V = \text{Span } S$$

Property 1.  $\mathbf{0} \in V$

Property 2.  $\mathbf{u}, \mathbf{v} \in V, \mathbf{u} + \mathbf{v} \in V$

Property 3.  $\mathbf{u} \in V, c\mathbf{u} \in V$





# Null Space

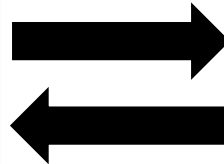
- The null space of a matrix  $A$  is the solution set of  $A\mathbf{x}=\mathbf{0}$ . It is denoted as  $\text{Null } A$ .

$$\text{Null } A = \{ \mathbf{v} \in \mathcal{R}^n : A\mathbf{v} = \mathbf{0} \}$$

The solution set of the homogeneous linear equations  $A\mathbf{v} = \mathbf{0}$ .

- $\text{Null } A$  is a subspace

A linear function is  
one-to-one



Null space only  
contain  $\mathbf{0}$

# Null Space - Example

$$T : \mathcal{R}^3 \rightarrow \mathcal{R}^2 \text{ with } T \left( \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right) = \begin{bmatrix} x_1 - x_2 + 2x_3 \\ -x_1 + x_2 - 3x_3 \end{bmatrix}$$

Find a generating set for the null space of  $T$ .

The null space of  $T$  is the set of solutions to  $A\mathbf{x} = \mathbf{0}$

$$A = \begin{bmatrix} 1 & -1 & 2 \\ -1 & 1 & -3 \end{bmatrix} \longrightarrow R = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{array}{rcl} x_1 & = & x_2 \\ \hline x_1 & - & x_2 & = & 0 \\ x_3 & = & 0 \end{array} \longrightarrow \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

a generating set for the null space

# Column Space and Row Space

- Column space of a matrix  $A$  is the span of its columns. It is denoted as  $\text{Col } A$ .

$$A \in \mathcal{R}^{m \times n} \Rightarrow \text{Col } A = \{A\mathbf{v} : \mathbf{v} \in \mathcal{R}^n\}$$

If matrix  $A$  represents a function

$\text{Col } A$  is the range of the function

- Row space of a matrix  $A$  is the span of its rows. It is denoted as  $\text{Row } A$ .

$$\text{Row } A = \text{Col } A^T$$

# Column Space = Range

- The range of a linear transformation is the same as the column space of its matrix.

**Linear Transformation**

$$T \left( \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \right) = \begin{bmatrix} x_1 + 2x_2 + x_3 - x_4 \\ 2x_1 + 4x_2 - 8x_4 \\ 2x_3 + 6x_4 \end{bmatrix}$$

**Standard matrix**

$$A = \begin{bmatrix} 1 & 2 & 1 & -1 \\ 2 & 4 & 0 & -8 \\ 0 & 0 & 2 & 6 \end{bmatrix} \Rightarrow \text{Range of } T = \text{Span} \left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 4 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ -8 \\ 6 \end{bmatrix} \right\}$$

# RREF

- Original Matrix  $A$  v.s. its RREF  $R$ 
  - Columns:
    - The relations between the columns are the same.
    - The span of the columns are different.
  - Rows:
    - The relations between the rows are changed.
    - The span of the rows are the same.

$$\text{Col } A \neq \text{Col } R$$

$$\text{Row } A = \text{Row } R$$

# Consistent

$Ax = b$  have solution (consistent)

$b$  is the linear combination of columns of  $A$

$b$  is in the span of the columns of  $A$

$b$  is in  $\text{Col } A$

$$A = \begin{bmatrix} 1 & 2 & 1 & -1 \\ 2 & 4 & 0 & -8 \\ 0 & 0 & 2 & 6 \end{bmatrix} \quad \mathbf{u} = \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} \in \text{Col } A? \quad \mathbf{v} = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix} \in \text{Col } A?$$

Solving  $Ax = u$

$$\text{RREF}([A \ u]) = \begin{bmatrix} 1 & 2 & 0 & -4 & 0 \\ 0 & 0 & 1 & 3 & 0 \\ 0 & 0 & 0 & 0 & \textcircled{1} \end{bmatrix}$$

Solving  $Ax = v$

$$\text{RREF}([A \ v]) = \begin{bmatrix} 1 & 2 & 0 & -4 & 0.5 \\ 0 & 0 & 1 & 3 & 1.5 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

# Conclusion: Subspace is Closed under addition and multiplication

